

7) Introduction to scattering

I) Classification of scattering problems

Scattering = open systems = systems coupled to external propagating modes

= we probe the system from the exterior (incident field)

currents are induced inside the system and radiate out (scattered field)

incident field + scattered field = total field (the one satisfying $\nabla \cdot \mathbf{E} + \text{BCs}$)

* 2 possibilities after fixing the frequency

1) We couple to the system via a finite number of ports $m \in \mathbb{N}$



m - port scattering

1 port = 1 mode carrying forward and backward waves

ex: electrical networks & transmission lines

dielectric resonators & optical fibers

ring resonator

Si waveguide

2) We are in free space (infinite number of modes = radiation continuum)

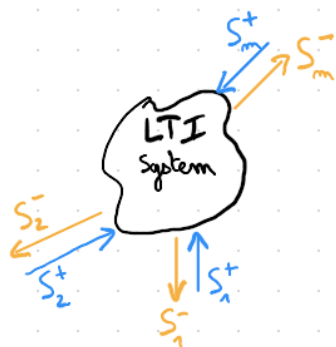


free space scattering

ex: radars, scattering of sunlight by small particles in the sky.

II) Linear M-port scattering

1. The scattering matrix



LTI: linear time-invariant,

$S_i^+ \in \mathbb{C}$: incident wave amplitude at port $i \in \llbracket 1, m \rrbracket$

$S_i^- \in \mathbb{C}$: outgoing —————

Convention : S_i^+ is normalized such that $|S_i^+|^2 = S_i^{+*} S_i^+$ is the incident/outgoing power at port i .

Linearity $\Rightarrow \exists S /$

$$\vec{S}_- = S \vec{S}_+$$

$m \times m$ scattering matrix

$$\vec{S}_+ = [S_1^+, S_2^+, \dots, S_m^+]^T \quad m \times 1 \text{ column vector}$$

2. Energy conservation

2.

$$\vec{S}_+^\dagger \vec{S}_+ = \sum_{i=1}^m S_i^{+*} S_i^+ = \sum_{i=1}^m |S_i^+|^2 \quad \text{total incident power}$$

$$\vec{S}_-^\dagger \vec{S}_- = \sum_{i=1}^m |S_i^-|^2 \quad \text{total outgoing power}$$

$$\begin{aligned} \text{Energy conservation} &\Leftrightarrow \vec{S}_+^\dagger \vec{S}_+ = \vec{S}_-^\dagger \vec{S}_- \quad \forall \vec{S}_+ \\ &\Leftrightarrow \vec{S}_+^\dagger \vec{S}_+ = (S \vec{S}_+)^dagger (S \vec{S}_+) = \vec{S}_+^\dagger S^\dagger S \vec{S}_+ \quad \forall \vec{S}_+ \\ &\Leftrightarrow \underline{S^\dagger S = \mathbb{1}}, \quad \underline{S \text{ is unitary}} \end{aligned}$$

S conserves the power flux $\Leftrightarrow$ S is unitary

In particular: $\begin{cases} \text{losses are negligible} \\ \text{gain \& loss compensate} \end{cases} \Rightarrow S \text{ is unitary}$

Some useful mathematical properties of unitary matrices:

1. $S^\dagger S = \mathbb{1} = S S^\dagger$

2. $S^{-1} = S^\dagger$

3. $|\det S| = 1$

4. $\exists$ an orthonormal basis of eigenvectors of S with eigenvalues lying on the unit circle

5. S has a decomposition of the form $S = V D V^\dagger$ with V unitary and D is diagonal unitary.

6. $\exists$ H Hermitian such that $S = e^{iH}$ (matrix exponential)

2. General parametrization of 2×2 unitary matrices: let $a, b \in \mathbb{C}$, $|a|^2 + |b|^2 = 1$

$$U = \begin{pmatrix} a & b \\ -e^{j\psi} b^* & e^{j\psi} a^* \end{pmatrix}, \text{ with } \underline{\det U = e^{j\psi}} \Rightarrow 4 \text{ parameters}$$

For unitary scattering, we write $a = r e^{j\alpha}$, $b = t e^{j\beta}$ with

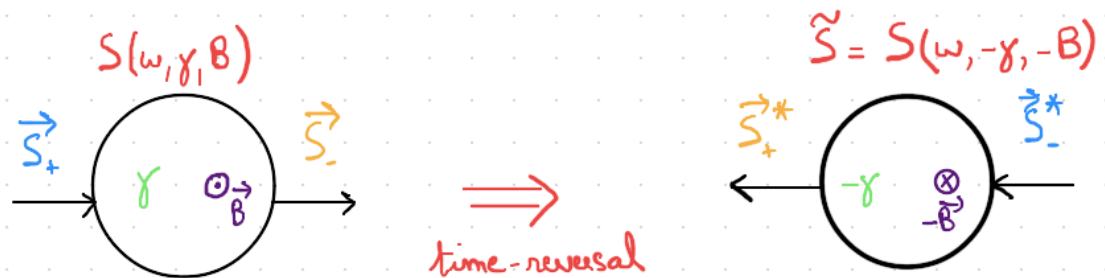
$r = \cos\theta$, $t = \sin\theta$. Then we get:

$$S = \begin{pmatrix} r e^{j\alpha} & t e^{j\beta} \\ e^{j\psi} r e^{-j\alpha} & e^{j\psi} t e^{-j\beta} \end{pmatrix}$$

3. Time-reversal symmetry

3. Consider a general m -port scattering process described by $S(\omega, \gamma, B)$ where $\omega \in \mathbb{R}$ is the frequency and (γ, B) are two different sources of broken time-reversal symmetry:

- * γ describes absorption or amplification ($\gamma > 0$ or $\gamma < 0$), which contributes to an imaginary symmetric term to the Hamiltonian (non-Hermitian) or to the non-unitarity of S .
- * B describes a time-odd parameter (e.g. magneto-optical effect, Aharonov Bohm phase, etc) that contributes to an imaginary anti-symmetric term to the Hamiltonian, i.e. does not break unitarity of S .



NB: The effect of time reversal on the complex signal amplitudes $\vec{S}_\pm$ is complex conjugation since $t \rightarrow -t$ effectively conjugate the temporal exponent $e^{j\omega t}$ and reverse the propagation vector k .

$$3. \text{ Thus } \begin{cases} \vec{S}_- = S(\omega, \gamma, B) \vec{S}_+ \\ \vec{S}_+^* = \tilde{S} \vec{S}_-^* \end{cases} \Rightarrow \begin{cases} \vec{S}_- = S \vec{S}_+ \\ \tilde{S}^{-1} \vec{S}_+^* = \vec{S}_-^* \Leftrightarrow \vec{S}_- = \tilde{S}^{-1*} \vec{S}_+^* \end{cases}$$

$$\Rightarrow (S - \tilde{S}^{-1*}) \vec{S}_+ = \vec{0} \quad \forall \vec{S}_+ \Rightarrow S = \tilde{S}^{-1*} \Rightarrow \tilde{S} = S^{*-1}$$

$$\Rightarrow \boxed{\tilde{S} = S(\omega, -\gamma, -B) = [S^*(\omega, \gamma, B)]^{-1}}$$

This equation just describes how time-reversal transforms S .

Now, if a system has time-reversal symmetry then $S = \tilde{S}$

$$\text{which implies } \begin{cases} S(\omega, \gamma, B) = S(\omega, -\gamma, -B) & (1) \\ \text{AND } S(\omega, \gamma, B) = [S^*(\omega, \gamma, B)]^{-1} & (2) \end{cases}$$

If we believe in the fact that S cannot have the same value at $+B$ and $-B$,

and for $+\gamma$ and $-\gamma$, then (1) implies $\gamma = B = 0$.

$$(2) \Rightarrow S = S^{*-1} \text{ or } S^{-1} = S^*$$

$$\boxed{\text{TRS} \Leftrightarrow \begin{aligned} \gamma = B = 0 \\ S^{-1} = S^* \end{aligned}}$$

4. Reciprocity

4. If S is flux preserving and time reversal symmetric then

$$S^{-1} = S^{\dagger} = S^* \Rightarrow \underline{S = S^T} \quad \text{reciprocity condition}$$

⚠ this is only a sufficient condition: systems with $B = 0$ and $\gamma \neq 0$ are also reciprocal (see Lorentz reciprocity theorem, valid in the presence of losses). This is a consequence of the Onsager relation:

$$S(\omega, \gamma, -B) = S^T(\omega, \gamma, B)$$

whose proof can be found in my Ph.D thesis, chap 2 [UT Austin]

$$S = S^T \Rightarrow B = 0 \text{ but not } \gamma = 0.$$

4. example: Can lossless 2 port systems be non-reciprocal?

Lossless 2-port:
$$S = \begin{pmatrix} re^{j\alpha} & te^{j\beta} \\ -e^{j\psi-j\beta} & e^{j\psi-j\alpha} \\ e^{j\psi-j\beta} & re^{j\alpha} \end{pmatrix}$$

Yes! but only in phase (non-reciprocal phase shifters)

⇒ The gyrator $\boxed{\rightarrow \pi \rightarrow}$, $S = \begin{pmatrix} 0 & 1 \\ j\pi & 0 \end{pmatrix}$ is lossless

⇒ The isolator $\rightarrow \triangle$, $S = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ must be lossy

$\triangle \rightarrow$, $S = \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}$ also!

What about 3 ports?

⇒ The circulator $S = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$ is unitary non-reciprocal



Rq: If I match port 3, creating a 2 port system between 1 & 2, I get an isolator.

Is it unitary? No, absorption occurs now at the matched port...

[[A few additional remarks (only for interested students!)

1. Another relation, called classical microreversibility, exists:

$$S(\omega, -\gamma, B) = [S^*(\omega, \gamma, B)]^{-1}$$

Proof: hard exercise!

2. Parity exchange left and right: $PS(\omega, \gamma(x), B(x)) = \Gamma_x S(\omega, \gamma(-x), B(-x)) \Gamma_x$

assuming S is written as $S = \begin{pmatrix} r & t' \\ t & r' \end{pmatrix}$ where r, r', t, t'

are blocks describing reflection & transmission when probed

from left/right (dimensions $N \times N$) and $\Gamma_x = \begin{pmatrix} 0 & \mathbb{1}_N \\ \mathbb{1}_N & 0 \end{pmatrix}$

$N = \frac{m}{2}$ modes on each side in x direction.

3 Parity time acts on S as:

$$\begin{aligned} PT S(\omega, \gamma(x), B(x)) &= \Gamma_x [S^*(\omega, \gamma(-x), B(-x))]^{-1} \Gamma_x \\ &= \Gamma_x S(\omega, -\gamma(-x), -B(-x)) \Gamma_x \end{aligned}$$

PT symmetry implies $\gamma(x) = -\gamma(-x), B(x) = -B(-x)$.

$$\Gamma_x S \Gamma_x = S \quad]]$$

5. Scattering time

* 2 port case: excitation from port 1

$$S_1^+ = e^{j(\omega t - kx)}$$

$$S_1^- = r e^{j(\omega t - kx + \phi_r)}$$

$$S_2^+ = 0$$

$$S_2^- = t e^{j(\omega t - kx + \phi_t)}$$

definition: $\tau_r = \frac{\partial \phi_r}{\partial \omega}$ $\tau_t = \frac{\partial \phi_t}{\partial \omega}$

Wigner-Smith time delays (>0 or <0)

* m-port generalisation

Let's introduce the Wigner-Smith time delay operator for any unitary matrix S :

$$Q_w = -j S^+ \frac{\partial S}{\partial \omega} = -j S^{-1} \frac{\partial S}{\partial \omega}$$

Properties:

1) Q is Hermitian

2) It's eigenvectors are scattering states with well defined scattering times, given by the associated eigenvalues.

Proof:

$$1) S^\dagger S = \mathbb{1} \Rightarrow \frac{\partial}{\partial \omega} (S^\dagger S) = 0 \Rightarrow \frac{\partial S^\dagger}{\partial \omega} S + S^\dagger \frac{\partial S}{\partial \omega} = 0$$

$$\Rightarrow \left(S^\dagger \frac{\partial S}{\partial \omega} \right)^\dagger + S^\dagger \frac{\partial S}{\partial \omega} = 0 \Rightarrow -j S^\dagger \frac{\partial S}{\partial \omega} = +j \left(S^\dagger \frac{\partial S}{\partial \omega} \right)^\dagger$$

$$\Rightarrow -j S^\dagger \frac{\partial S}{\partial \omega} = \left(-j S^\dagger \frac{\partial S}{\partial \omega} \right)^\dagger \Rightarrow Q_\omega = Q_\omega^\dagger \quad \text{QED}$$

$$2) \text{ eigenvectors of } Q_\omega : Q_\omega \vec{u}_m = \tau_m \vec{u}_m = -j S^{-1} \frac{\partial S}{\partial \omega} \vec{u}_m$$

Noting $\vec{v}_m$ the output state corresponding to $\vec{u}_m$, $\vec{v}_m = S \vec{u}_m$

at a frequency ω_0

$$+j \tau_m \vec{v}_m(\omega_0) = \frac{\partial S}{\partial \omega} \bigg|_{\omega_0} \vec{u}_m(\omega_0) = \left| \frac{\partial \vec{v}_m(\omega_0)}{\partial \omega} \right|_{\omega_0} = +j \tau_m \vec{v}_m(\omega_0)$$

$$\Rightarrow \vec{v}_m(\omega_0 + \Delta\omega) \simeq \vec{v}_m(\omega_0) e^{+j \tau_m \Delta\omega} \quad \text{with } \tau_m = \frac{d\varphi_{\text{out}}}{d\omega}$$

$\Rightarrow$ the scattering state is robust and its time delay is τ_m

6. Generalized Wigner-Smith operator

Let α be a parameter influencing the scattering process (ex: ω , as before, or the position x or angle θ of a given scatterer), and let $C_\alpha = -j \frac{d}{d\alpha}$ the conjugate operator to the observable α (related to the conjugated observable, ex t, p_x, L_x). $p_x \sim -j \frac{d}{dx}$

We define the generalized Wigner-Smith operator for unitary S matrices:

$$Q_\alpha = -j S^{-1} \frac{\partial S}{\partial \alpha}$$

Theorem: For an input state $\vec{u}$ associated with $\vec{v} = S\vec{u}$

$$\vec{u}^\dagger Q_\alpha \vec{u} = \vec{u}^\dagger C_\alpha \vec{u} - \vec{v}^\dagger C_\alpha \vec{v} = \langle C_\alpha \rangle_{\text{in}} - \langle C_\alpha \rangle_{\text{out}}$$

namely $\vec{u}^\dagger Q_\alpha \vec{u}$ measures the change of expectation value $\langle C_\alpha \rangle$ of the conjugate variable to α as the state $\vec{u}$ scatters into $\vec{v}$.

ex: $\alpha = x$, the position of a scatterer. $\vec{u}^\dagger Q_\alpha \vec{u}$ is the expected momentum shift that the eigenstate experiences, i.e. the momentum transferred to the scatterer.

[see example discussed in class]

proof: We need to use shift operators. For a function f of $x \in \mathbb{R}$, there exists an operator T_t that shifts $f(x)$ by t namely $T_t f(x) = f(x+t)$.

Lemma: The expression of T_t is $T_t = e^{t \frac{d}{dx}}$, which means
$$T_t = \sum_{n=0}^{+\infty} \frac{t^n}{n!} \frac{d^n}{dx^n}$$

[Proof of Lemma: Since all well-behaved functions can be expanded as $f(x) = \sum_{N=0}^{\infty} \frac{f^{(N)}(0)}{N!} x^N$, we can restrict the proof to

$$\begin{aligned} f &= x^N \\ T_t x^N &= \sum_{n=0}^{+\infty} \frac{t^n}{n!} \frac{d^n}{dx^n} x^N = \sum_{n=0}^N \frac{t^n}{n!} \frac{N!}{(N-n)!} x^{N-n} = \sum_{n=0}^N \binom{N}{n} x^{N-n} t^n \\ &= (x+t)^N \quad (\text{Binomial theorem}) \end{aligned}$$

f could be a complex vector like $\vec{u}$, T_t just applies to each components. For a function of α ,
$$T_{\Delta\alpha} = e^{\Delta\alpha \frac{d}{d\alpha}} = e^{j\Delta\alpha C_\alpha}$$

How to shift an operator O ? We must shift all matrix elements

$$\begin{aligned} \langle \psi_j | O | \psi_i \rangle &= \langle \psi_j(\alpha) | O | \psi_i(\alpha) \rangle \rightarrow \langle \psi_j(\alpha + \Delta\alpha) | O | \psi_i(\alpha + \Delta\alpha) \rangle \\ &= \langle T_{\Delta\alpha} \psi_j | O | T_{\Delta\alpha} \psi_i \rangle = \langle \psi_j | T^{-1} O T | \psi_i \rangle \end{aligned}$$

$$\Rightarrow \quad \underline{O(\alpha + \Delta\alpha) = T_{\Delta\alpha}^{-1} O(\alpha) T_{\Delta\alpha} = e^{-j\Delta\alpha C_\alpha} O e^{j\Delta\alpha C_\alpha}}$$

In particular, for S : $S(\alpha + \Delta\alpha) = e^{-j\Delta\alpha C_\alpha} S(\alpha) e^{j\Delta\alpha C_\alpha}$

If $\Delta\alpha$ is small $e^{\Delta\alpha \frac{d}{d\alpha}} \approx \mathbb{1} + \Delta\alpha \frac{d}{d\alpha} = \mathbb{1} + j\Delta\alpha C_\alpha$

$$\Rightarrow S(\alpha + \Delta\alpha) \approx (\mathbb{1} - j\Delta\alpha C_\alpha) S(\alpha) (\mathbb{1} + j\Delta\alpha C_\alpha) \\ \approx S(\alpha) - j\Delta\alpha C_\alpha S_\alpha + j S(\alpha) \Delta\alpha C_\alpha + O(\Delta\alpha^2)$$

$$\Rightarrow \frac{dS}{d\alpha} = \lim_{\alpha \rightarrow 0} \frac{S(\alpha + \Delta\alpha) - S(\alpha)}{\Delta\alpha} = j S(\alpha) C_\alpha - j C_\alpha S(\alpha)$$

$$\Rightarrow Q_\alpha = -j S^\dagger \frac{dS}{d\alpha} = -j S^\dagger (j S C_\alpha - C_\alpha S)$$

$$\Rightarrow \underline{Q_\alpha = C_\alpha - S^\dagger C_\alpha S}$$

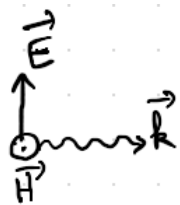
For an incident state $\vec{a}$, $\vec{b} = S\vec{a}$

$$\langle a | Q_\alpha | a \rangle = \vec{a}^\dagger Q_\alpha \vec{a} = \vec{a}^\dagger C_\alpha \vec{a} - \underbrace{\vec{a}^\dagger S^\dagger}_{\vec{b}^\dagger} \underbrace{C_\alpha S}_{\vec{b}} \vec{a}$$

$$\Rightarrow \langle Q_\alpha \rangle_{in} = \langle C_\alpha \rangle_{in} - \langle C_\alpha \rangle_{out} \quad [QED]$$

This is in particular true for an eigenstate $\vec{u}$, $\vec{u}^\dagger Q_\alpha \vec{u} = \theta_\alpha$.

III) Free-space scattering



(ϵ_0, μ_0)

The impinging field does not match the BC on the obstacle surface

$$\Rightarrow \begin{cases} \vec{E}_{\text{tot}} = \vec{E}_{\text{inc}} + \vec{E}_{\text{scat}} \\ \vec{H}_{\text{tot}} = \vec{H}_{\text{inc}} + \vec{H}_{\text{scat}} \end{cases}$$

$$\Rightarrow \vec{S}_{\text{tot}} = \frac{1}{2} \vec{E}_{\text{tot}} \times \vec{H}_{\text{tot}}^* = \frac{1}{2} (\vec{E}_{\text{inc}} \times \vec{H}_{\text{inc}}^*) + \frac{1}{2} (\vec{E}_{\text{scat}} \times \vec{H}_{\text{scat}}^*) + \frac{1}{2} (\vec{E}_{\text{inc}} \times \vec{H}_{\text{scat}}^* + \vec{E}_{\text{scat}} \times \vec{H}_{\text{inc}}^*)$$

$$\Rightarrow \text{Re} \left[\oint d\vec{S} \cdot \vec{S}_{\text{tot}} \right] = \underbrace{\text{Re} \left[\frac{1}{2} \oint (\vec{E}_{\text{tot}} \times \vec{H}_{\text{tot}}^*) \cdot d\vec{S} \right]}_{W_{\text{abs}}} = \underbrace{\text{Re} \left[\frac{1}{2} \oint (\vec{E}_{\text{inc}} \times \vec{H}_{\text{inc}}^*) \cdot d\vec{S} \right]}_0 + \underbrace{\text{Re} \left[\frac{1}{2} \oint (\vec{E}_{\text{scat}} \times \vec{H}_{\text{scat}}^*) \cdot d\vec{S} \right]}_{W_{\text{scat}}} + \underbrace{\text{Re} \left[\frac{1}{2} \oint d\vec{S} \cdot (\vec{E}_{\text{inc}} \times \vec{H}_{\text{scat}}^* + \vec{E}_{\text{scat}} \times \vec{H}_{\text{inc}}^*) \right]}_{-W_{\text{ext}}}$$

$$\Rightarrow \underline{W_{\text{ext}} = W_{\text{scat}} + W_{\text{abs}}} \quad \begin{array}{l} \text{extracted power from the incident field} \\ = \text{EXTINCTION POWER} \end{array}$$

* Remarques

- Lossless case : $W_{abs} = 0 \Rightarrow W_{ext} = W_{abs}$

- Scattering cross-section:

$$\sigma_{scat} = \frac{W_{scat}}{|S_{inc}|} = \frac{\text{total scattered power}}{\text{impinging power density}} \equiv \left[\frac{W}{W/m^2} \right] \equiv [m^2]$$

$$Q_{scat} = \frac{C_{scat}}{\pi a^2} [1] \text{ scattering efficiency}$$

$$\sigma_{ext} = \frac{W_{ext}}{|S_{inc}|} [m^2]$$

$$\Rightarrow \sigma_{ext} = \sigma_{scat} + \sigma_{abs}$$

- σ depends on the object's geometry